# Foxboro I/A APC Configuration Tips

David Johnson Director of BD DCS & Process Industries EOSYS





### **David Johnson** Director of BD DCS & Process Industries

EOSYS

## **Using Supervisory Setpoint Control**

- Became usable by humans once auto-acknowledge was added
- You don't "HAVE" to have APC, but you can't connect the SUP\_IN parameter
- PID has 2 options
  - Manipulate the Setpoint, or
  - Manipulate the Output
- AOUT has 1 option
  - Manipulate the Output
- Tremendous possibilities w/built-in Bumpless transfers



## SSC Adds 2 "New" PIDA Modes

- 1. Manual
- 2. Automatic w Local Setpoint
- 3. Automatic w Remote Setpoint
- 4. Automatic w Supervisory Setpoint
- 5. Tracking w AOUT in Manual
- 6. Tracking w AOUT in Supervisory Control



## **PIDA SSC Block Parameters**

Table 99-1. PIDA Block Parameters

Name	Description	Туре	Accessibility	Default	Units/Range
INPUTS					
SE	supervisory enable	Boolean	no-con/set	o	0 to 1
SUP_IN	supervisory setpoint	real	con/no-set	<mark>0.0</mark>	RI1
INITSE	initial SE	short	no-con/no-set	0	0 to 2
SUPGRP	supervisory group	short	no-con/no-set	1	1 to 8
SUPOPT	supervisory option	short	no-con/no-set	0	0 to 4
OUTPUTS					
SUPBCO	supervisory back calculation real		con/no-set	0	RI1

## **AOUT SSC Block Parameters**

Configurable P	arameters					
INITSE	initial SE	short	no-con/no-set	0	0 to 2	
SE	supervisory enable	boolean	no-con/set	0	0 to 1	
SUPOPT	supervisory option	short	no-con/no-set	0	0, 1, 3	
SUPGRP	supervisory group	short	no-con/no-set	1	1 to 8	
Non-Configura	able Parameters					
SUP IN	supervisory input	real	con/set	0.0	RI1	
SUPBCO	supervisory back calc out	real	no-con/no-set	0	RII	

## HOW TO CONFIGURE

## Configuration

**SUPGRP = 1-8** Enable with CP SSC Groups 1-8

#### SUPOPT = 0-4

- 0 No SSC
- 1 SPC Set Point Control w/ explicit handshaking
- 2 DDC Direct Digital Control w/ explicit handshaking
- 3 SPC Set Point Control w/ implicit acknowledge
- 4 DDC Direct Digital Control w/ implicit acknowledge

#### SE = 0-1

- 0 Disabled
- 1 Enabled

#### SUP\_IN

 Can't be connected – but can be set with OPC or HLBL or OMSETs





#### **PIDA in MANUAL**

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "D" in the Faceplates indicate SSC is "D" isabled

This shows normal PIDA Manual Operation



## **PIDA in AUTO**

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "D" in the Faceplates indicate SSC is "D" isabled

This shows normal PIDA AUTO Operation



### **PIDA in REMOTE**

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "D" in the Faceplates indicateSSC is "D" isabled

This shows normal PIDA Remote Operation



#### PIDA Transitioning

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "E" in the PIDA Faceplate indicates SSC is "E"nabled

The PIDA is waiting for a SUP\_IN change. Even though we show a 45 – the SUP\_IN must change before PIDA goes into SSC



#### PIDA in SSC CONTROL

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "C" in the PIDA Faceplate indicates SSC is in "C"losed Loop

The PIDA is now in SSC control



## **AOUT to MAN**

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "E" in the PIDA Faceplate indicates SSC is still "E"nabled

The AOUT is in MANUAL and the PIDA is now tracking with SSC still enabled



#### AOUT to Transitioning

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "E" in the PIDA Faceplate indicates SSC is still "E"nabled

The AOUT is in AUTO and SSC is "E"nabled waiting for a new SUP\_IN. The AOUT also indicates it is "H"olding its output



#### **AOUT to SSC**

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "E" in the PIDA Faceplate indicates SSC is still "E"nabled

The AOUT is in AUTO and SSC is in "C"losed loop



## AOUT back to AUTO

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "E" in the PIDA Faceplate indicates SSC is still "E"nabled. Waiting for a change in SUP\_IN to go back to "C"losed Loop

The AOUT is in AUTO



## AOUT back to AUTO

PIDA is in SUPGRP 1 AOUT is in SUPGRP 2

The "C" in the PIDA Faceplate indicates SSC is back to "C"losed Loop control

The AOUT is in AUTO

# QUESTIONS?

